

Title	EQUIGEODESICS ON GENERALIZED FLAG MANIFOLDS WITH G_2 -TYPE t -ROOTS
Author(s)	Statha, Marina
Citation	Osaka Journal of Mathematics. 57(4) p.871-p.888
Issue Date	2020-10
oaire:version	VoR
URL	https://doi.org/10.18910/77235
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EQUIGEODESICS ON GENERALIZED FLAG MANIFOLDS WITH G_2 -TYPE \mathfrak{t} -ROOTS

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(Received January 15, 2019, revised June 19, 2019)

Abstract

We study homogeneous curves in generalized flag manifolds G/K with G_2 -type \mathfrak{t} -roots, which are geodesics with respect to each G -invariant metric on G/K . These curves are called *equigeodesics*. The tangent space of such flag manifolds splits into six isotropy summands, which are in one-to-one correspondence with \mathfrak{t} -roots. Also, these spaces are a generalization of the exceptional full flag manifold G_2/T . We give a characterization for structural equigeodesics for flag manifolds with G_2 -type \mathfrak{t} -roots, and we give for each such flag manifold, a list of subspaces in which the vectors are structural equigeodesic vectors.

1. Introduction

Let $(G/K, g)$ be a Riemannian homogeneous space. A geodesic $\gamma(t)$ through the origin $o = eK$ is called a *homogeneous geodesic* if it is an orbit of a one-parameter subgroup of G , i.e., $\gamma(t) = (\exp tX) \cdot o$, where X is a non-zero vector in the Lie algebra \mathfrak{g} of G . If all geodesics on G/K are homogeneous geodesics the homogeneous space is called a *g.o. manifold* (from “geodesic orbit”). The terminology was introduced by O. Kowalski and L. Vanhecke in [10], who initiated a systematic study of such spaces. Examples of such spaces are the symmetric spaces, the weakly symmetric spaces and the naturally reductive spaces.

In [6] the authors studied homogeneous curves on generalized flag manifolds that are geodesics with respect to each invariant metric on the flag manifold. These curves are called *equigeodesics*. Since the infinitesimal generator of the one parameter subgroup is an element of the Lie algebra of G , it is natural to characterize the equigeodesics in terms of their infinitesimal generator. This allows us to use a Lie theoretical approach for the study of homogeneous geodesics on flag manifolds. The infinitesimal generator of an equigeodesic is called *equigeodesic vector*. An algebraic characterization of equigeodesic vectors on generalized flag manifolds is given in [6].

Recall that a *generalized flag manifold* is a homogeneous space G/K where G is a compact, semisimple Lie group and K is the centralizer of a torus in G . Actually a vector is equigeodesic if and only if it is a solution of an algebraic system of equations whose variables are the components of the vector. However, there exist some subspaces of the tangent space $\mathfrak{m} \cong T_o(G/K)$ of the flag manifold G/K , all of whose elements are equigeodesic vectors. The existence of such subspaces depends on the geometric structure of the G/K . These equigeodesic vectors are called *structural equigeodesic*. The authors in [8] have provided a version of the previously formula for equigeodesic vectors on generalized flag

manifolds with two isotropy summands. Later in [11] the authors gave a general formula for finding equigeodesic vectors on generalized flag manifolds with second Betti number equal to one (that is flag manifolds which are determined by painting one black node their Dynkin diagram). More precisely, they found families of subspaces in which all vectors are structural equigeodesic vectors, on generalized flag manifolds associated to exceptional Lie groups F_4, E_6 and E_7 with three isotropy summands, that is $F_4 / (U(2) \times SU(3))$, $E_6 / (U(2) \times SU(3) \times SU(3))$ and $E_7 / (U(3) \times SU(5))$.

In the present article we study equigeodesics on generalized flag manifolds with G_2 -type t -roots. In particular, for such type of flag manifolds we describe the families of subspaces in which all elements are structural equigeodesic vectors. We know from [5] that generalized flag manifolds G/K with G_2 -type t -roots have six isotropy summands and correspond to painted Dynkin diagrams with two black nodes with Dynkin marks 2 and 3. In particular, these are the generalized flag manifolds $F_4(\alpha_3, \alpha_4)$, $E_6(\alpha_3, \alpha_6)$, $E_7(\alpha_5, \alpha_6)$ and $E_8(\alpha_1, \alpha_2)$. Here with $G(\alpha_{i_0}, \alpha_{j_0})$ we denote the flag manifold $M = G/K$ where we have painted two black nodes on the Dynkin diagram of G .

In Theorems 3.5 and 3.6 of the present paper we provide a method to obtain structural equigeodesic vectors (cf. Propositions 4.1 and 4.2). For $F_4(\alpha_3, \alpha_4)$ and $E_6(\alpha_3, \alpha_6)$ we find all subspaces in which the vectors are structural equigeodesics. These are described in Tables 3, 4 and 5. For the flag manifold $E_7(\alpha_5, \alpha_6)$ we describe all the roots that satisfy Theorem 3.5 and therefore we can describe by simple calculation all root spaces whose vectors are structural equigeodesics (we give some of them). Finally, for the flag manifold $E_8(\alpha_1, \alpha_2)$ we give some of the roots that satisfy Theorem 3.6. In conclusion we have the following:

Theorem 1.1. *The generalized flag manifolds $F_4 / (U(3) \times U(1))$, $E_6 / (U(3) \times U(3))$, $E_7 / (U(6) \times U(1))$ and $E_8 / (E_6 \times U(1) \times U(1))$ admit non trivial structural equigeodesic vectors.*

2. Generalized Flag Manifolds

2.1. Description of flag manifolds in terms of painted Dynkin diagrams. Let \mathfrak{g} and \mathfrak{k} be the Lie algebras of G and K respectively and $\mathfrak{g}^{\mathbb{C}}, \mathfrak{k}^{\mathbb{C}}$ be their complexifications. We choose a maximal torus T in G and let \mathfrak{h} be the Lie algebra of T . Then the complexification $\mathfrak{h}^{\mathbb{C}}$ is a Cartan subalgebra of $\mathfrak{g}^{\mathbb{C}}$. Let $R \subset (\mathfrak{h}^{\mathbb{C}})^*$ be the root system of $\mathfrak{g}^{\mathbb{C}}$ relative to the Cartan subalgebra $\mathfrak{h}^{\mathbb{C}}$ and consider the root space decomposition $\mathfrak{g}^{\mathbb{C}} = \mathfrak{h}^{\mathbb{C}} \oplus \sum_{\alpha \in R} \mathfrak{g}_{\alpha}^{\mathbb{C}}$, where $\mathfrak{g}_{\alpha}^{\mathbb{C}} = \{X \in \mathfrak{g}^{\mathbb{C}} : \text{ad}(H)X = \alpha(H)X, \text{ for all } H \in \mathfrak{h}^{\mathbb{C}}\}$ denotes the root space associated to a root α . Assume that $\mathfrak{g}^{\mathbb{C}}$ is semisimple, so the Killing form B of $\mathfrak{g}^{\mathbb{C}}$ is non degenerate, and we establish a natural isomorphism between $\mathfrak{h}^{\mathbb{C}}$ and the dual space $(\mathfrak{h}^{\mathbb{C}})^*$ as follows: for every $\alpha \in (\mathfrak{h}^{\mathbb{C}})^*$ we define $H_{\alpha} \in \mathfrak{h}^{\mathbb{C}}$ by the equation $B(H, H_{\alpha}) = \alpha(H)$, for all $H \in \mathfrak{h}^{\mathbb{C}}$. We take a Weyl basis $E_{\alpha} \in \mathfrak{g}_{\alpha}^{\mathbb{C}}$ ($\alpha \in R$) with $B(E_{\alpha}, E_{-\alpha}) = -1$ and $[E_{\alpha}, E_{-\alpha}] = -H_{\alpha}$. Then $\mathfrak{g}_{\alpha}^{\mathbb{C}} = \mathbb{C}E_{\alpha}$ and

$$(1) \quad [E_{\alpha}, E_{\beta}] = \begin{cases} N_{\alpha\beta}E_{\alpha+\beta} & \text{if } \alpha, \beta, \alpha + \beta \in R \\ 0 & \text{if } \alpha, \beta \in R, \alpha + \beta \notin R, \end{cases}$$

where the structure constants $N_{\alpha\beta} \in \mathbb{R}$ are such that $N_{\alpha\beta} = 0$ if $\alpha, \beta \in R$, $\alpha + \beta \notin R$, and $N_{\alpha\beta} = -N_{\beta\alpha}$, $N_{\alpha\beta} = N_{-\alpha, -\beta} \in \mathbb{R}$ if $\alpha, \beta, \alpha + \beta \in R$. It is clear that $N_{\alpha\beta} \neq 0$, if $\alpha, \beta, \alpha + \beta \in R$ and so relation (1) implies that $[\mathfrak{g}_{\alpha}^{\mathbb{C}}, \mathfrak{g}_{\beta}^{\mathbb{C}}] = \mathfrak{g}_{\alpha+\beta}^{\mathbb{C}}$. Choose a basis $\Pi = \{\alpha_1, \dots, \alpha_{\ell}\}$ ($\dim \mathfrak{h}^{\mathbb{C}} = \ell$)

of simple roots for R , and let R^+ be a choice of positive roots. Set $A_\alpha = E_\alpha + E_{-\alpha}$ and $B_\alpha = \sqrt{-1}(E_\alpha - E_{-\alpha})$, where $\alpha \in R^+$. Then the real subalgebra \mathfrak{g} is given by

$$(2) \quad \mathfrak{g} = \mathfrak{h} \oplus \sum_{\alpha \in R^+} (\mathbb{R}A_\alpha + \mathbb{R}B_\alpha) = \mathfrak{h} \oplus \sum_{\alpha \in R^+} \mathfrak{u}_\alpha.$$

Note that \mathfrak{g} , as a real form of $\mathfrak{g}^\mathbb{C}$ is the fixed point set of the conjugation $\tau : \mathfrak{g}^\mathbb{C} \rightarrow \mathfrak{g}^\mathbb{C}$, which without loss of generality can be assumed to be such that $\tau(E_\alpha) = E_{-\alpha}$.

Since $\mathfrak{h}^\mathbb{C} \subset \mathfrak{t}^\mathbb{C} \subset \mathfrak{g}^\mathbb{C}$, there is a closed subsystem R_K of R such that $\mathfrak{t}^\mathbb{C} = \mathfrak{h}^\mathbb{C} \oplus \sum_{\alpha \in R_K} \mathfrak{g}_\alpha^\mathbb{C}$. In particular, we can always find a subset $\Pi_K \subset \Pi$ such that $R_K = R \cap \langle \Pi_K \rangle = \{\beta \in R : \beta = \sum_{\alpha_i \in \Pi_K} k_i \alpha_i, k_i \in \mathbb{Z}\}$, where $\langle \Pi_K \rangle$ is the space of roots generated by Π_K with integer coefficients. The complex Lie algebra $\mathfrak{t}^\mathbb{C}$ is a maximal reductive subalgebra of $\mathfrak{g}^\mathbb{C}$ and thus it admits the decomposition $\mathfrak{t}^\mathbb{C} = \mathfrak{z}(\mathfrak{t}^\mathbb{C}) \oplus \mathfrak{t}_{ss}^\mathbb{C}$, where $\mathfrak{z}(\mathfrak{t}^\mathbb{C})$ is the center of $\mathfrak{t}^\mathbb{C}$ and $\mathfrak{t}_{ss}^\mathbb{C} = [\mathfrak{t}^\mathbb{C}, \mathfrak{t}^\mathbb{C}]$ is its semisimple part. Note that $\mathfrak{t}_{ss}^\mathbb{C}$ is given by $\mathfrak{t}_{ss}^\mathbb{C} = \mathfrak{h}' \oplus \sum_{\alpha \in R_K} \mathfrak{g}_\alpha^\mathbb{C}$, where $\mathfrak{h}' = \sum_{\alpha \in \Pi_K} \mathbb{C}H_\alpha \subset \mathfrak{h}^\mathbb{C}$ is a Cartan subalgebra of $\mathfrak{t}_{ss}^\mathbb{C}$. In fact, R_K is the root system of the semisimple part $\mathfrak{t}_{ss}^\mathbb{C}$ and Π_K is a corresponding basis. Thus we easily conclude that $\dim_{\mathbb{C}} \mathfrak{h}' = \text{card } \Pi_K$, where $\text{card } \Pi_K$ denotes the cardinality of the set Π_K . Let K be the connected Lie subgroup of G generated by $\mathfrak{k} = \mathfrak{t}^\mathbb{C} \cap \mathfrak{g}$. Then the homogeneous manifold $M = G/K$ is a flag manifold, and any flag manifold is defined in this way, i.e. by the choice of a triple $(\mathfrak{g}^\mathbb{C}, \Pi, \Pi_K)$.

Set $\Pi_M = \Pi \setminus \Pi_K$, and $R_M = R \setminus R_K$, such that $\Pi = \Pi_K \cup \Pi_M$, and $R = R_K \cup R_M$, respectively. Roots in R_M are called *complementary roots*, and they play an important role in the geometry of $M = G/K$. For example, let \mathfrak{m} the orthogonal complement of \mathfrak{k} in \mathfrak{g} with respect to B . Then we have $[\mathfrak{k}, \mathfrak{m}] \subset \mathfrak{m}$ where $\mathfrak{m} \cong T_o(G/K)$. We set $R_M^+ = R^+ \setminus R_K^+$ where R_K^+ is the system of positive roots of $\mathfrak{t}^\mathbb{C}$ ($R_K^+ \subset R^+$). Then

$$(3) \quad \mathfrak{m} = \sum_{\alpha \in R_M^+} (\mathbb{R}A_\alpha + \mathbb{R}B_\alpha).$$

The complexification is given as $\mathfrak{m}^\mathbb{C} = \sum_{\alpha \in R_M} \mathbb{C}E_\alpha$, and the set $\{E_\alpha : \alpha \in R_M\}$ is a basis of $\mathfrak{m}^\mathbb{C}$.

Now if we assume that $\Pi_M = \Pi \setminus \Pi_K = \{\alpha_{i_1}, \dots, \alpha_{i_r}\}$, where $1 \leq i_1 < \dots < i_r \leq \ell$ we set, for some integers j_1, \dots, j_r with $(j_1, \dots, j_r) \neq (0, \dots, 0)$

$$(4) \quad R^{\mathfrak{m}}(j_1, \dots, j_r) = \left\{ \sum_{j=1}^r m_j \alpha_j \in R^+ : m_{i_1} = j_1, \dots, m_{i_r} = j_r \right\} \subset R^+.$$

Note that $R_M^+ = R^+ \setminus R_K^+ = \bigcup_{j_1, \dots, j_r} R^{\mathfrak{m}}(j_1, \dots, j_r)$. For any $R^{\mathfrak{m}}(j_1, \dots, j_r) \neq \emptyset$, we define an $\text{Ad}(K)$ -invariant subspace $\mathfrak{m}(j_1, \dots, j_r)$ of \mathfrak{g} by

$$(5) \quad \mathfrak{m}(j_1, \dots, j_r) = \sum_{\alpha \in R^{\mathfrak{m}}(j_1, \dots, j_r)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\}.$$

Then we have a decomposition of \mathfrak{m} into mutually non equivalent irreducible $\text{Ad}(K)$ -modules $\mathfrak{m}(j_1, \dots, j_r)$:

$$\mathfrak{m} = \sum_{j_1, \dots, j_r} \mathfrak{m}(j_1, \dots, j_r).$$

We conclude that all information contained in $\Pi = \Pi_K \cup \Pi_M$ can be presented graphically

by the painted Dynkin diagram of $M = G/K$.

DEFINITION 2.1. Let $\Gamma = \Gamma(\Pi)$ be the Dynkin diagram of the fundamental system Π . By painting in black the nodes of Γ corresponding to Π_M , we obtain the painted Dynkin diagram of the flag manifold G/K . In this diagram the subsystem Π_K is determined as the subdiagram of white roots.

Conversely, given a painted Dynkin diagram, in order to obtain the corresponding flag manifold $M = G/K$ we are working as follows: We define G as the unique simply connected Lie group corresponding to the underlying Dynkin diagram $\Gamma = \Gamma(\Pi)$. The connected Lie subgroup $K \subset G$ is defined by using the additional information $\Pi = \Pi_K \cup \Pi_M$ encoded into the painted Dynkin diagram. The semisimple part of K is obtained from the (not necessarily connected) subdiagram of white roots, and each black root, i.e. each root in Π_M , gives rise to one $U(1)$ -summand. Thus the painted Dynkin diagram determines the isotropy subgroup K and the space $M = G/K$ completely. By using certain rules to determine whether different painted Dynkin diagrams define isomorphic flag manifolds (see [1]), one can obtain all flag manifolds G/K of a compact simple Lie group G .

From now on we denote the flag manifold $M = G/K$ with $G \in \{B_\ell, C_\ell, D_\ell, F_4, E_6, E_7, E_8\}$, by $G(\alpha_{i_0})$ if we have painted one node of $\Gamma(\Pi)$, that is $\Pi_M = \Pi \setminus \Pi_K = \{\alpha_{i_0}\}$ and by $G(\alpha_{i_0}, \alpha_{j_0})$ if we have painted two nodes of $\Gamma(\Pi)$, that is $\Pi_M = \Pi \setminus \Pi_K = \{\alpha_{i_0}, \alpha_{j_0}\}$.

We close this subsection with the next lemma which gives us some information about the Lie algebra structure of \mathfrak{g} .

Lemma 2.2. *The Lie brackets among the elements of the basis $\{A_\alpha, B_\alpha, \sqrt{-1}H_\beta : \alpha \in R^+ \text{ and } \beta \in \Pi\}$ of \mathfrak{g} are given as follows:*

$$\begin{aligned} [A_\alpha, A_\beta] &= N_{\alpha,\beta} A_{\alpha+\beta} + N_{-\alpha,\beta} A_{\alpha-\beta}, & [\sqrt{-1}H_\alpha, A_\beta] &= \beta(H_\alpha) B_\beta \\ [B_\alpha, B_\beta] &= -N_{\alpha,\beta} A_{\alpha+\beta} - N_{\alpha,-\beta} A_{\alpha-\beta}, & [\sqrt{-1}H_\alpha, B_\beta] &= -\beta(H_\alpha) A_\beta \\ [A_\alpha, B_\beta] &= N_{\alpha,\beta} B_{\alpha+\beta} + N_{\alpha,-\beta} B_{\alpha-\beta}, & [A_\alpha, B_\alpha] &= 2\sqrt{-1}H_\alpha, \end{aligned}$$

where $\alpha + \beta, \alpha - \beta$ are roots.

Proof. We will prove three of the above relations and the others can be obtained by a similar method. For the first we have:

$$\begin{aligned} [A_\alpha, A_\beta] &= [E_\alpha + E_{-\alpha}, E_\beta + E_{-\beta}] = N_{\alpha,\beta} E_{\alpha+\beta} + N_{\alpha,-\beta} E_{\alpha-\beta} + N_{-\alpha,\beta} E_{-\alpha+\beta} + N_{-\alpha,-\beta} E_{-\alpha-\beta} \\ &= N_{\alpha,\beta} E_{\alpha+\beta} + N_{-\alpha,\beta} E_{\alpha-\beta} + N_{-\alpha,\beta} E_{-\alpha+\beta} + N_{\alpha,\beta} E_{-(\alpha+\beta)} \\ &= N_{\alpha,\beta} A_{\alpha+\beta} + N_{-\alpha,\beta} A_{\alpha-\beta}. \end{aligned}$$

For the second we have:

$$\begin{aligned} [\sqrt{-1}H_\alpha, A_\beta] &= [\sqrt{-1}H_\alpha, E_\beta + E_{-\beta}] = \sqrt{-1}[H_\alpha, E_\beta] + \sqrt{-1}[H_\alpha, E_{-\beta}] \\ &= \sqrt{-1}\beta(H_\alpha)E_\beta - \sqrt{-1}\beta(H_\alpha)E_{-\beta} \\ &= \beta(H_\alpha)B_\beta. \end{aligned}$$

Finally, we prove the last relation:

$$\begin{aligned}
[A_\alpha, B_\alpha] &= [E_\alpha + E_{-\alpha}, \sqrt{-1}(E_\alpha - E_{-\alpha})] = -\sqrt{-1}[E_\alpha, E_{-\alpha}] + \sqrt{-1}[E_{-\alpha}, E_\alpha] \\
&= \sqrt{-1}H_\alpha + \sqrt{-1}H_\alpha = 2\sqrt{-1}H_\alpha.
\end{aligned}$$

□

2.2. \mathfrak{t} -roots and isotropy summands. We study the isotropy representation of a generalized flag manifold $M = G/K$ of a compact simple Lie group G in terms of \mathfrak{t} -roots. In order to realise the decomposition of \mathfrak{m} into irreducible $\text{Ad}(K)$ -modules we use the center \mathfrak{t} of the real Lie algebra \mathfrak{k} . For simplicity, we fix a system of simple roots $\Pi = \{\alpha_1, \dots, \alpha_r, \phi_1, \dots, \phi_k\}$ of R , such that $r + k = \ell = \text{rk } \mathfrak{g}^\mathbb{C}$ and we assume that $\Pi_K = \{\phi_1, \dots, \phi_k\}$ is a basis of the root system R_K of K so $\Pi_M = \Pi \setminus \Pi_K = \{\alpha_1, \dots, \alpha_r\}$. Let $\Lambda_1, \dots, \Lambda_r$ be the fundamental weights corresponding to the simple roots of Π_M , i.e. the linear forms defined by $\frac{2(\Lambda_i, \alpha_j)}{(\alpha_j, \alpha_j)} = \delta_{ij}$, $(\Lambda_j, \phi_i) = 0$, where (α, β) denotes the inner product on $(\mathfrak{h}^\mathbb{C})^*$ given by $(\alpha, \beta) = (H_\alpha, H_\beta)$, for all $\alpha, \beta \in (\mathfrak{h}^\mathbb{C})^*$. Then the $\{\Lambda_i : 1 \leq i \leq r\}$ is a basis of the dual space \mathfrak{t}^* of \mathfrak{t} , $\mathfrak{t}^* = \sum_{i=1}^r \mathbb{R}\Lambda_i$ and $\dim \mathfrak{t}^* = \dim \mathfrak{t} = r$.

Consider now the linear restriction map $\kappa : \mathfrak{h}^* \rightarrow \mathfrak{t}^*$ defined by $\kappa(\alpha) = \alpha|_{\mathfrak{t}}$, and set $R_{\mathfrak{t}} = \kappa(R) = \kappa(R_M)$.

DEFINITION 2.3. The elements of $R_{\mathfrak{t}}$ are called *\mathfrak{t} -roots*.

The set $R_{\mathfrak{t}}$ is not in general a root system. An element $Y \in \mathfrak{t}$ is called *regular* if any \mathfrak{t} -root $\kappa(\alpha) = \xi$ ($\alpha \in R_M$) takes non zero value at Y , i.e. $\xi(Y) \neq 0$. A regular element defines an ordering in \mathfrak{t}^* and thus we obtain the splitting $R_{\mathfrak{t}} = R_{\mathfrak{t}}^+ \cup R_{\mathfrak{t}}^-$, where $R_{\mathfrak{t}}^+ = \{\xi \in R_{\mathfrak{t}} : \xi(Y) > 0\}$ and $R_{\mathfrak{t}}^- = \{\xi \in R_{\mathfrak{t}} : \xi(Y) < 0\}$. The \mathfrak{t} -roots $\xi \in R_{\mathfrak{t}}^+$ (resp. $\xi \in R_{\mathfrak{t}}^-$) will be called *positive* (resp. *negative*). Since $R_{\mathfrak{t}} = \kappa(R_M)$ it follows that $R_{\mathfrak{t}}^+ = \kappa(R_M^+)$, and since $R_M^- = -R_M^+ = \{-\alpha : \alpha \in R_M^+\}$, it is $R_{\mathfrak{t}}^- = \kappa(R_M^-)$.

DEFINITION 2.4. A \mathfrak{t} -root is called *simple* if it is not a sum of two positive \mathfrak{t} -roots.

The set of all simple \mathfrak{t} -roots is denoted as $\Pi_{\mathfrak{t}}$ and is a basis of \mathfrak{t}^* , in the sense that any \mathfrak{t} -root can be written as a linear combination of its elements with integer coefficients of the same sign. We will call the set $\Pi_{\mathfrak{t}}$ as a *\mathfrak{t} -basis*.

Proposition 2.5 ([3]). A \mathfrak{t} -basis $\Pi_{\mathfrak{t}}$ is obtained by restricting the roots of $\Pi_M = \Pi \setminus \Pi_K$ to \mathfrak{t} , that is $\Pi_{\mathfrak{t}} = \{\kappa(\alpha_i) = \bar{\alpha}_i = \alpha_i|_{\mathfrak{t}} : \alpha_i \in \Pi_M\}$.

As we saw the flag manifolds G/K are determined by pairs $(\mathfrak{g}, \Pi, \Pi_K)$. The number of $\text{ad}(\mathfrak{k})$ -submodules of $\mathfrak{m} \cong T_o(G/K)$ correspond to the *Dynkin mark* of the simple root we paint black on the Dynkin diagram. We recall the following definition

DEFINITION 2.6. The Dynkin mark of a simple root $\alpha_i \in \Pi$ ($i = 1, \dots, \ell$), is the positive integer m_i in the expression of the highest root $\tilde{\alpha} = \sum_{k=1}^{\ell} m_k \alpha_k$ in terms of simple roots. We will denote by Mrk the function $\text{Mrk} : \Pi \rightarrow \mathbb{Z}^+$ with $\text{Mrk}(\alpha_i) = m_i$.

By using the Proposition 2.5 we give a useful method to find the positive \mathfrak{t} -root $R_{\mathfrak{t}}^+$ of $\Pi_M = \{\alpha_i \in \Pi : \text{Mrk}(\alpha_i) = m_i\}$. The \mathfrak{t} -basis is $\Pi_{\mathfrak{t}} = \{\bar{\alpha}_i\}$, where $\kappa(\alpha_i) = \bar{\alpha}_i = \alpha_i|_{\mathfrak{t}}$ and $\mathfrak{t}^* = \mathbb{R}\bar{\alpha}_i$. We fix a positive root $\alpha = \sum_{j=1}^{\ell} k_j \alpha_j \in R^+$, with $k_j \leq m_j$ for all $j = 1, \dots, \ell$.

Then by the fact that $\kappa(R_K) = 0$ we have that for all $\alpha \in R_M$, $\kappa(\alpha) = \alpha|_{\mathfrak{t}} = k_i \bar{\alpha}_i$ with $1 \leq k_i \leq m_i$. Hence $R_{\mathfrak{t}}^+ = \{k_i \bar{\alpha}_i : 1 \leq k_i \leq m_i\} = \{\bar{\alpha}_i, 2\bar{\alpha}_i, \dots, m_i \bar{\alpha}_i\}$ and $\text{card} R_{\mathfrak{t}}^+ = m_i$. In case where $\Pi_M = \{\alpha_i, \alpha_j : \text{Mrk}(\alpha_i) = m_i, \text{Mrk}(\alpha_j) = m_j\}$ then $\Pi_{\mathfrak{t}} = \{\bar{\alpha}_i, \bar{\alpha}_j : i < j\}$, where $\kappa(\alpha_i) = \bar{\alpha}_i = \alpha_i|_{\mathfrak{t}}$, $\kappa(\alpha_j) = \bar{\alpha}_j = \alpha_j|_{\mathfrak{t}}$ and $\mathfrak{t}^* = \text{span}\{\bar{\alpha}_i, \bar{\alpha}_j\}$. Then for $\alpha \in R_M^+$ we have $\kappa(\alpha) = \alpha|_{\mathfrak{t}} = k_i \bar{\alpha}_i + k_j \bar{\alpha}_j$ where $0 \leq k_i \leq m_i$, $0 \leq k_j \leq m_j$ the coefficients k_i, k_j can not be simultaneously zero, so it is obvious that $\text{card} R_{\mathfrak{t}}^+ \geq 3$. For generalized flag manifold G/K with $b_2(G/K) \geq 3$ there are more than five \mathfrak{t} -roots ([4]).

A fundamental result about \mathfrak{t} -root is the following:

Proposition 2.7 ([2]). *There exists a one-to-one correspondence between \mathfrak{t} -roots ξ and irreducible $\text{ad}(\mathfrak{f}^{\mathbb{C}})$ -submodules \mathfrak{m}_{ξ}^1 of the isotropy representation of $\mathfrak{m}^{\mathbb{C}}$, which is given by*

$$R_{\mathfrak{t}} \ni \xi \leftrightarrow \mathfrak{m}_{\xi} = \sum_{\alpha \in R_M : \kappa(\alpha) = \xi} \mathbb{C} E_{\alpha}.$$

Thus $\mathfrak{m}^{\mathbb{C}} = \bigoplus_{\xi \in R_{\mathfrak{t}}} \mathfrak{m}_{\xi}$. Moreover, these submodules are non equivalent as $\text{ad}(\mathfrak{f}^{\mathbb{C}})$ -modules.

In order to obtain a decomposition of the real $\text{Ad}(K)$ -module \mathfrak{m} in terms of \mathfrak{t} -roots, we use the complex conjugation τ of $\mathfrak{g}^{\mathbb{C}}$ with respect to \mathfrak{g} (note that τ interchanges $\mathfrak{g}_{\alpha}^{\mathbb{C}}$ and $\mathfrak{g}_{-\alpha}^{\mathbb{C}}$). Moreover, for a complex subspace V of $\mathfrak{g}^{\mathbb{C}}$ we denote by V^{τ} the set of all fixed points of τ . Then, we can write

$$(6) \quad \mathfrak{m} = \bigoplus_{\xi \in R_{\mathfrak{t}}^+} (\mathfrak{m}_{\xi} \oplus \mathfrak{m}_{-\xi})^{\tau}.$$

Let us assume for simplicity that $R_{\mathfrak{t}}^+ = \{\xi_1, \dots, \xi_s\}$. In this case Proposition 2.7 and relations (3), (6) imply that the real irreducible $\text{ad}(\mathfrak{f})$ -submodule $\mathfrak{m}_i = (\mathfrak{m}_{\xi_i} \oplus \mathfrak{m}_{-\xi_i})^{\tau}$ ($1 \leq i \leq s$) which corresponds to a positive \mathfrak{t} -root ξ_i , is necessarily of the form

$$(7) \quad \mathfrak{m}_i = \sum_{\{\alpha \in R_M^+ : \kappa(\alpha) = \xi_i\}} \{\mathbb{R} A_{\alpha} + \mathbb{R} B_{\alpha}\}.$$

By summarizing, we have the following proposition

Proposition 2.8 ([4]). *Let $M = G/K$ be a generalized flag manifold defined by a subset $\Pi_K \subset \Pi$ such that $\Pi_M = \Pi \setminus \Pi_K = \{\alpha_{i_1}, \dots, \alpha_{i_r}\}$ with $1 \leq i_1 < \dots < i_r \leq \ell$. Assume that $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{m}$ is a B -orthogonal reductive decomposition. Then*

- (1) *There exists a natural one-to-one correspondence between elements of the set $R^{\mathfrak{m}}(j_1, \dots, j_r)$ and the set of positive \mathfrak{t} -roots $R_{\mathfrak{t}}^+ = \{\xi_1, \dots, \xi_s\}$. Therefore, there is a decomposition of \mathfrak{m} into s mutually non-equivalent irreducible $\text{Ad}(K)$ -modules $\mathfrak{m} = \sum_{\xi \in R_{\mathfrak{t}}^+} (\mathfrak{m}_{\xi} \oplus \mathfrak{m}_{-\xi})^{\tau} = \sum_{i=1}^s (\mathfrak{m}_{\xi_i} \oplus \mathfrak{m}_{-\xi_i})^{\tau} = \sum_{j_1, \dots, j_r} \mathfrak{m}(j_1, \dots, j_r)$*
- (2) *The dimensions of the real $\text{Ad}(K)$ -modules \mathfrak{m}_i ($i = 1, \dots, s$) corresponding to the \mathfrak{t} -root $\xi_i \in R_{\mathfrak{t}}^+$ are given by $\dim_{\mathbb{R}} \mathfrak{m}_i = 2 \text{card} \{\alpha \in R_M^+ : \kappa(\alpha) = \xi_i\} = 2 \text{card} R^{\mathfrak{m}}(j_1, \dots, j_r)$, for appropriate positive integers j_1, \dots, j_r .*
- (3) *Any G -invariant Riemannian metric g on G/K is given by*

$$g = \sum_{\xi \in R_{\mathfrak{t}}^+} x_{\xi} B|_{(\mathfrak{m}_{\xi} \oplus \mathfrak{m}_{-\xi})^{\tau}} = \sum_{i=1}^s x_{\xi_i} B|_{(\mathfrak{m}_{\xi_i} \oplus \mathfrak{m}_{-\xi_i})^{\tau}} = \sum_{j_1, \dots, j_r} x_{j_1, \dots, j_r} B|_{\mathfrak{m}(j_1, \dots, j_r)}$$

¹We mean that $[\mathfrak{f}^{\mathbb{C}}, \mathfrak{m}_{\xi}] \subset \mathfrak{m}_{\xi}$ for all $\xi \in R_{\mathfrak{t}}$.

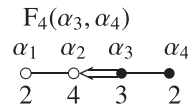
for positive real numbers $x_\xi, x_{\xi_i}, x_{j_1, \dots, j_r}$. The G -invariant Riemannian metrics on $M = G/K$ are parametrized by s real positive parameters.

2.3. Generalized flag manifolds with G_2 -type \mathfrak{t} -roots. A system of positive roots of the Lie group G_2 is given by $\{\alpha_1, \alpha_2, \alpha_1 + \alpha_2, 2\alpha_1 + \alpha_2, 3\alpha_1 + \alpha_2, 3\alpha_1 + 2\alpha_2\}$, with highest root $\tilde{\alpha} = 3\alpha_1 + 2\alpha_2$. The corresponding painted Dynkin diagram of the full flag manifold G_2/T is

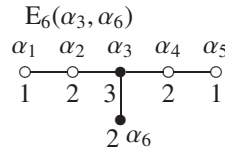


From the paper [5] we have that flag manifolds with G_2 -type \mathfrak{t} -roots system satisfy $\Pi \setminus \Pi_K = \{\alpha_i, \alpha_j : \text{Mrk}(\alpha_i) = 3, \text{Mrk}(\alpha_j) = 2\}$, and are the following:

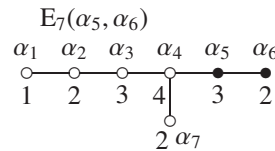
The highest root $\tilde{\alpha}$ of F_4 is given by $\tilde{\alpha} = 2\alpha_1 + 4\alpha_2 + 3\alpha_3 + 2\alpha_4$, and we have the following painted Dynkin diagram



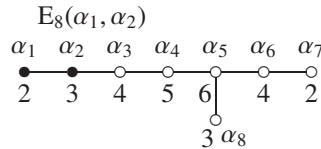
The highest root $\tilde{\alpha}$ of E_6 is given by $\tilde{\alpha} = \alpha_1 + 2\alpha_2 + 3\alpha_3 + 2\alpha_4 + \alpha_5 + 2\alpha_6$ and we have the following painted Dynkin diagram



The highest root $\tilde{\alpha}$ of E_7 is given by $\tilde{\alpha} = \alpha_1 + 2\alpha_2 + 3\alpha_3 + 4\alpha_4 + 3\alpha_5 + 2\alpha_6 + 2\alpha_7$ and we have the following painted Dynkin diagram



The highest root $\tilde{\alpha}$ of E_8 is given by $\tilde{\alpha} = 2\alpha_1 + 3\alpha_2 + 4\alpha_3 + 5\alpha_4 + 6\alpha_5 + 4\alpha_6 + 2\alpha_7 + 3\alpha_8$ and we have the following painted Dynkin diagram



For $\Pi \setminus \Pi_K = \{\alpha_i, \alpha_j\}$ we put $\bar{\alpha}_i = \kappa(\alpha_i)$ and $\bar{\alpha}_j = \kappa(\alpha_j)$. We list the sets of all positive \mathfrak{t} -roots $R_{\mathfrak{t}}^+$ in Table 1, which we separate into Type I and Type II.

From Proposition 2.7 it is easy to see that the isotropy representation of the above homogeneous spaces is written as a direct sum of six non equivalent $\text{Ad}(K)$ -invariant isotropy summands. For flag manifolds of Type I we set

Table 1. Positive t-roots R_t^+ for pairs (Π, Π_K)

Type I	Set of all positive t-roots R_t^+
$F_4(\alpha_3, \alpha_4)$	$\{\bar{\alpha}_3, \bar{\alpha}_4, \bar{\alpha}_3 + \bar{\alpha}_4, 2\bar{\alpha}_3 + \bar{\alpha}_4, 3\bar{\alpha}_3 + \bar{\alpha}_4, 3\bar{\alpha}_3 + 2\bar{\alpha}_4\}$
$E_6(\alpha_3, \alpha_6)$	$\{\bar{\alpha}_3, \bar{\alpha}_6, \bar{\alpha}_3 + \bar{\alpha}_6, 2\bar{\alpha}_3 + \bar{\alpha}_6, 3\bar{\alpha}_3 + \bar{\alpha}_6, 3\bar{\alpha}_3 + 2\bar{\alpha}_6\}$
$E_7(\alpha_5, \alpha_6)$	$\{\bar{\alpha}_5, \bar{\alpha}_6, \bar{\alpha}_5 + \bar{\alpha}_6, 2\bar{\alpha}_5 + \bar{\alpha}_6, 3\bar{\alpha}_5 + \bar{\alpha}_6, 3\bar{\alpha}_5 + 2\bar{\alpha}_6\}$
G_2	$\{\bar{\alpha}_1, \bar{\alpha}_2, \bar{\alpha}_1 + \bar{\alpha}_2, 2\bar{\alpha}_1 + \bar{\alpha}_2, 3\bar{\alpha}_1 + \bar{\alpha}_2, 3\bar{\alpha}_1 + 2\bar{\alpha}_2\}$
Type II	Set of all positive t-roots R_t^+
$E_8(\alpha_1, \alpha_2)$	$\{\bar{\alpha}_1, \bar{\alpha}_2, \bar{\alpha}_1 + \bar{\alpha}_2, \bar{\alpha}_1 + 2\bar{\alpha}_2, \bar{\alpha}_1 + 3\bar{\alpha}_2, 2\bar{\alpha}_1 + 3\bar{\alpha}_2\}$

Table 2. Dimensions of irreducible summands with G_2 -type t-roots

Type I	$m(1, 0)$	$m(0, 1)$	$m(1, 1)$	$m(2, 1)$	$m(3, 1)$	$m(3, 2)$
$F_4(\alpha_3, \alpha_4)$	12	2	12	12	2	2
$E_6(\alpha_3, \alpha_6)$	18	2	18	18	2	2
$E_7(\alpha_5, \alpha_6)$	30	2	30	30	2	2
G_2	2	2	2	2	2	2
Type II	$m(1, 0)$	$m(0, 1)$	$m(1, 1)$	$m(1, 2)$	$m(1, 3)$	$m(2, 3)$
$E_8(\alpha_1, \alpha_2)$	2	54	54	54	2	2

$$\begin{aligned}
 (8) \quad & m(1, 0) = (m_{\bar{\alpha}_i} + m_{-\bar{\alpha}_i})^\tau, & m(0, 1) &= (m_{\bar{\alpha}_j} + m_{-\bar{\alpha}_j})^\tau, \\
 & m(1, 1) = (m_{\bar{\alpha}_i + \bar{\alpha}_j} + m_{-\bar{\alpha}_i - \bar{\alpha}_j})^\tau, & m(2, 1) &= (m_{2\bar{\alpha}_i + \bar{\alpha}_j} + m_{-\bar{\alpha}_i - \bar{\alpha}_j})^\tau, \\
 & m(3, 1) = (m_{3\bar{\alpha}_i + \bar{\alpha}_j} + m_{-\bar{\alpha}_i - \bar{\alpha}_j})^\tau, & m(3, 2) &= (m_{3\bar{\alpha}_i + 2\bar{\alpha}_j} + m_{-\bar{\alpha}_i - 2\bar{\alpha}_j})^\tau,
 \end{aligned}$$

and for Type II we set

$$\begin{aligned}
 (9) \quad & m(1, 0) = (m_{\bar{\alpha}_i} + m_{-\bar{\alpha}_i})^\tau, & m(0, 1) &= (m_{\bar{\alpha}_j} + m_{-\bar{\alpha}_j})^\tau, \\
 & m(1, 1) = (m_{\bar{\alpha}_i + \bar{\alpha}_j} + m_{-\bar{\alpha}_i - \bar{\alpha}_j})^\tau, & m(1, 2) &= (m_{\bar{\alpha}_i + 2\bar{\alpha}_j} + m_{-\bar{\alpha}_i - 2\bar{\alpha}_j})^\tau, \\
 & m(1, 3) = (m_{\bar{\alpha}_i + 3\bar{\alpha}_j} + m_{-\bar{\alpha}_i - 3\bar{\alpha}_j})^\tau, & m(2, 3) &= (m_{2\bar{\alpha}_i + 3\bar{\alpha}_j} + m_{-\bar{\alpha}_i - 3\bar{\alpha}_j})^\tau.
 \end{aligned}$$

By using tables of positive roots (eg. Table B in Appendix of [[7], pp. 528–531]), we obtain the dimensions of these spaces as shown in Table 2.

We consider the generalized flag manifold $M = G/K$ with G_2 -type t-roots. As we have seen we have the decomposition of $\mathfrak{m} \cong T_o(G/K)$ into six irreducible non equivalent $\text{Ad}(K)$ -modules as follows:

$$(10) \quad \text{Type I} : \mathfrak{m} = m(1, 0) \oplus m(0, 1) \oplus m(1, 1) \oplus m(2, 1) \oplus m(3, 1) \oplus m(3, 2)$$

$$(11) \quad \text{Type II} : \mathfrak{m} = m(1, 0) \oplus m(0, 1) \oplus m(1, 1) \oplus m(1, 2) \oplus m(1, 3) \oplus m(2, 3).$$

For Type I we set $m_1 = m(1, 0)$, $m_2 = m(0, 1)$, $m_3 = m(1, 1)$, $m_4 = m(2, 1)$, $m_5 = m(3, 1)$, $m_6 = m(3, 2)$, and for Type II we set $n_1 = m(1, 0)$, $n_2 = m(0, 1)$, $n_3 = m(1, 1)$, $n_4 = m(1, 2)$, $n_5 = m(1, 3)$ and $n_6 = m(2, 3)$.

We now compute the Lie brackets $[m_i, m_j]$ and $[n_i, n_j]$ among the real irreducible submodules m_i and n_i of \mathfrak{m} . According to (7), each real submodule m_i (or n_i) associated to the positive t-root ξ_i can be expressed in terms of root vectors $E_{\pm\alpha}$ ($\alpha \in R_M^+$), such that $\kappa(\alpha) = \xi_i$. So from (1) we can compute the brackets $[m_i, m_j]$ (or $[n_i, n_j]$), for suitable root vectors E_α .

Lemma 2.9. *Let $M = G/K$ be the flag manifold of Type I. Then we obtain that $[m_i, m_i] \subset \mathfrak{k}$ for $1 \leq i \leq 6$, and*

$$\begin{aligned}
 (12) \quad & [\mathfrak{m}_1, \mathfrak{m}_2] \subset \mathfrak{m}_3 & [\mathfrak{m}_2, \mathfrak{m}_3] \subset \mathfrak{m}_1 & [\mathfrak{m}_3, \mathfrak{m}_4] \subset \mathfrak{m}_1 \oplus \mathfrak{m}_6 & [\mathfrak{m}_4, \mathfrak{m}_5] \subset \mathfrak{m}_1 \\
 & [\mathfrak{m}_1, \mathfrak{m}_3] \subset \mathfrak{m}_2 \oplus \mathfrak{m}_4 & [\mathfrak{m}_2, \mathfrak{m}_4] \subset \mathfrak{k} & [\mathfrak{m}_3, \mathfrak{m}_5] \subset \mathfrak{k} & [\mathfrak{m}_4, \mathfrak{m}_6] \subset \mathfrak{m}_3 \\
 & [\mathfrak{m}_1, \mathfrak{m}_4] \subset \mathfrak{m}_3 \oplus \mathfrak{m}_5 & [\mathfrak{m}_2, \mathfrak{m}_5] \subset \mathfrak{m}_6 & [\mathfrak{m}_3, \mathfrak{m}_6] \subset \mathfrak{m}_4 & [\mathfrak{m}_5, \mathfrak{m}_6] \subset \mathfrak{m}_2 \\
 & [\mathfrak{m}_1, \mathfrak{m}_5] \subset \mathfrak{m}_4 & [\mathfrak{m}_2, \mathfrak{m}_6] \subset \mathfrak{m}_5 & & \\
 & [\mathfrak{m}_1, \mathfrak{m}_6] \subset \mathfrak{k}. & & &
 \end{aligned}$$

Lemma 2.10. *Let $M = G/K$ be a flag manifold of Type II. Then we obtain that $[\mathfrak{n}_i, \mathfrak{n}_i] \subset \mathfrak{k}$ for $1 \leq i \leq 6$, and*

$$\begin{aligned}
 (13) \quad & [\mathfrak{n}_1, \mathfrak{n}_2] \subset \mathfrak{n}_3 & [\mathfrak{n}_2, \mathfrak{n}_3] \subset \mathfrak{n}_1 \oplus \mathfrak{n}_4 & [\mathfrak{n}_3, \mathfrak{n}_4] \subset \mathfrak{n}_2 \oplus \mathfrak{n}_6 & [\mathfrak{n}_4, \mathfrak{n}_5] \subset \mathfrak{n}_2 \\
 & [\mathfrak{n}_1, \mathfrak{n}_3] \subset \mathfrak{n}_2 & [\mathfrak{n}_2, \mathfrak{n}_4] \subset \mathfrak{n}_3 \oplus \mathfrak{n}_5 & [\mathfrak{n}_3, \mathfrak{n}_5] \subset \mathfrak{k} & [\mathfrak{n}_4, \mathfrak{n}_6] \subset \mathfrak{n}_3 \\
 & [\mathfrak{n}_1, \mathfrak{n}_4] \subset \mathfrak{k} & [\mathfrak{n}_2, \mathfrak{n}_5] \subset \mathfrak{n}_4 & [\mathfrak{n}_3, \mathfrak{n}_6] \subset \mathfrak{n}_4 & [\mathfrak{n}_5, \mathfrak{n}_6] \subset \mathfrak{n}_1 \\
 & [\mathfrak{n}_1, \mathfrak{n}_5] \subset \mathfrak{n}_6 & [\mathfrak{n}_2, \mathfrak{n}_6] \subset \mathfrak{k} & & \\
 & [\mathfrak{n}_1, \mathfrak{n}_6] \subset \mathfrak{n}_5. & & &
 \end{aligned}$$

3. Equigeodesics

Let G/K be a generalized flag manifold equipped with a G -invariant metric g . It is known that such metrics are in one-to-one correspondence with $\text{Ad}(K)$ -invariant scalar products $\langle \cdot, \cdot \rangle$ on $\mathfrak{m} \cong T_o(G/K)$ ([9, Proposition 3.1]). These in turn correspond $\text{Ad}(K)$ -equivariant, positive definite, symmetric operators $\Lambda : \mathfrak{m} \rightarrow \mathfrak{m}$ determined by $\langle \cdot, \cdot \rangle = Q(\Lambda \cdot, \cdot)$, where $Q = -B$, the negative of the Killing form on \mathfrak{g} . A curve of the form $\gamma(t) = (\exp tX) \cdot o$ is called *equigeodesic* on G/K if it is a geodesic with respect to each invariant metric on G/K . The vector X is called *equigeodesic vector*. The following proposition gives us an algebraic characterization of equigeodesic vectors.

Proposition 3.1 ([6]). *Let G/K be a reductive homogeneous space with reductive decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{m}$ and $X \in \mathfrak{m}$ be a non-zero vector. Then X is a equigeodesic vector if and only if*

$$(14) \quad [X, \Lambda X]_{\mathfrak{m}} = 0,$$

for each invariant metric Λ .

To solve equation (14) is equivalent to solve a non linear algebraic system of equations whose variables are the coefficients of the vector X . We consider the decomposition $\mathfrak{m} = \sum_{\alpha \in R_M^+} \mathfrak{m}_\alpha$ and the basis $\{A_\alpha, B_\alpha : \alpha \in R_M^+\}$. Then, by analysing the Lie brackets $[A_\alpha, B_\beta]$, $[A_\alpha, A_\beta]$, $[B_\alpha, B_\beta]$ described in (1) it is clear that if the structural constants $N_{\alpha, \beta}$, $N_{-\alpha, \beta}$, $N_{\alpha, -\beta}$ vanish (e.g. if $\alpha \pm \beta$ is not a root), then these brackets also vanish and the system can be simplified. In some cases (depending just on the \mathfrak{m}_i -parts of X) the nonlinear system vanishes completely (i.e. the system is identically zero). This motivates the following definition:

DEFINITION 3.2. An equigeodesic vector X is said to be

(a) structural if the algebraic system associated to equation (14) vanishes completely.

(b) algebraic if the coordinates of the vector X come from a solution of a (not identically zero) nonlinear algebraic system associated to equation (14).

REMARK 3.3. From the invariance of the metric Λ , we have that $\Lambda|_{\mathfrak{m}_i} = \lambda_i \text{Id}_{\mathfrak{m}_i}$, for some $\lambda_i > 0$, for each irreducible component of the isotropy representation. Therefore, if $X \in \mathfrak{m}_i$ then equation (14) is satisfied trivially.

We call an equigeodesic vector $X \in \mathfrak{m}$ *trivial* if $X \in \mathfrak{m}_i$ for some i , otherwise is said to be *non trivial*. It is obvious that the trivial equigeodesic vectors are structural equigeodesic vectors.

Lemma 3.4. *Let G/K be a generalized flag manifold with G_2 -type \mathfrak{t} -roots. A vector $X = \sum_{i=1}^6 X_{\mathfrak{m}_i} \in \mathfrak{m} = \bigoplus_{i=1}^6 \mathfrak{m}_i$ (resp. $X = \sum_{i=1}^6 X_{\mathfrak{n}_i} \in \mathfrak{n} = \bigoplus_{i=1}^6 \mathfrak{n}_i$) is equigeodesic if and only if*

$$(15) \quad [X_{\mathfrak{m}_i}, X_{\mathfrak{m}_j}] = 0, \quad (\text{resp. } [X_{\mathfrak{n}_i}, X_{\mathfrak{n}_j}] = 0)$$

where $1 \leq i < j \leq 6$.

Proof. If $\pi : \mathfrak{g} \rightarrow \mathfrak{m}$ is the projection onto \mathfrak{m} , then $\pi([X, \Lambda X]) = [X, \Lambda X]_{\mathfrak{m}}$. Assume that G/K is a flag manifold of Type I. Let $X = \sum_{i=1}^6 X_{\mathfrak{m}_i} \in \mathfrak{m} = \bigoplus_{i=1}^6 \mathfrak{m}_i$. Then

$$\begin{aligned} [X, \Lambda X]_{\mathfrak{m}} &= \pi([X, \Lambda X]) = \pi\left(\left[\sum_{i=1}^6 X_{\mathfrak{m}_i}, \Lambda\left(\sum_{i=1}^6 X_{\mathfrak{m}_i}\right)\right]\right) = \pi\left(\left[\sum_{i=1}^6 X_{\mathfrak{m}_i}, \sum_{i=1}^6 \lambda_i X_{\mathfrak{m}_i}\right]\right) \\ &= \sum_{i=2}^6 (\lambda_i - \lambda_1) \pi([X_{\mathfrak{m}_1}, X_{\mathfrak{m}_i}]) + \sum_{i=3}^6 (\lambda_i - \lambda_2) \pi([X_{\mathfrak{m}_2}, X_{\mathfrak{m}_i}]) + \cdots + (\lambda_6 - \lambda_5) \pi([X_{\mathfrak{m}_5}, X_{\mathfrak{m}_6}]) \\ &= (\lambda_2 - \lambda_1)[X_{\mathfrak{m}_1}, X_{\mathfrak{m}_2}] + (\lambda_3 - \lambda_1)[X_{\mathfrak{m}_1}, X_{\mathfrak{m}_3}] + (\lambda_4 - \lambda_1)[X_{\mathfrak{m}_1}, X_{\mathfrak{m}_4}] + (\lambda_5 - \lambda_1)[X_{\mathfrak{m}_1}, X_{\mathfrak{m}_5}] \\ &\quad + (\lambda_3 - \lambda_2)[X_{\mathfrak{m}_2}, X_{\mathfrak{m}_3}] + (\lambda_5 - \lambda_2)[X_{\mathfrak{m}_2}, X_{\mathfrak{m}_5}] + (\lambda_6 - \lambda_2)[X_{\mathfrak{m}_2}, X_{\mathfrak{m}_6}] + (\lambda_4 - \lambda_3)[X_{\mathfrak{m}_3}, X_{\mathfrak{m}_4}] \\ &\quad + (\lambda_6 - \lambda_3)[X_{\mathfrak{m}_3}, X_{\mathfrak{m}_6}] + (\lambda_5 - \lambda_4)[X_{\mathfrak{m}_4}, X_{\mathfrak{m}_5}] + (\lambda_6 - \lambda_4)[X_{\mathfrak{m}_4}, X_{\mathfrak{m}_6}] + (\lambda_6 - \lambda_5)[X_{\mathfrak{m}_5}, X_{\mathfrak{m}_6}]. \end{aligned}$$

From the bracket relations (12) we see that all the above brackets $[X_{\mathfrak{m}_i}, X_{\mathfrak{m}_j}]$ belong to \mathfrak{m} . We know that X is a equigeodesic vector if and only if $[X, \Lambda X]_{\mathfrak{m}} = 0$ for each invariant metric $\Lambda = \{\lambda_1, \dots, \lambda_6\}$ ($\lambda_1 > 0, \dots, \lambda_6 > 0$). This occurs if and only if $[X_{\mathfrak{m}_i}, X_{\mathfrak{m}_j}] = 0$, where $1 \leq i < j \leq 6$. Similarly, if G/K is a flag manifold of Type II we use bracket relations (13) and can show that the vector $X = \sum_{i=1}^6 X_{\mathfrak{n}_i} \in \mathfrak{n} = \bigoplus_{i=1}^6 \mathfrak{n}_i$ is equigeodesic if and only if $[X_{\mathfrak{n}_i}, X_{\mathfrak{n}_j}] = 0$ where $1 \leq i < j \leq 6$. \square

In the papers [8] and [11] the authors gave a family of structural equigeodesic vectors for the generalized flag manifolds G/K with two and s isotropy summands respectively, which depend only on the Lie algebra structure of \mathfrak{g} . The next theorem provides a family of structural equigeodesic vectors on generalized flag manifolds with G_2 -type \mathfrak{t} -roots.

Theorem 3.5. *Let G/K be a generalized flag manifold with G_2 -type \mathfrak{t} -roots and $\Pi_K = \Pi \setminus \{\alpha_{i_0}, \alpha_{j_0}\}$ of Type I. Let the positive roots $R^{\mathfrak{m}}(1, 0) = \{\beta_1^1, \dots, \beta_{k_1}^1\}$, $R^{\mathfrak{m}}(0, 1) = \{\beta_1^2, \dots, \beta_{k_2}^2\}$, $R^{\mathfrak{m}}(1, 1) = \{\beta_1^3, \dots, \beta_{k_3}^3\}$, $R^{\mathfrak{m}}(2, 1) = \{\beta_1^4, \dots, \beta_{k_4}^4\}$, $R^{\mathfrak{m}}(3, 1) = \{\beta_1^5, \dots, \beta_{k_5}^5\}$, $R^{\mathfrak{m}}(3, 2) = \{\beta_1^6, \dots, \beta_{k_6}^6\}$. Suppose that the set $\{\beta_{i_1}^1, \beta_{i_2}^2, \dots, \beta_{i_6}^6 : 1 \leq i_1 \leq k_1, \dots, 1 \leq i_6 \leq k_6\}$ satisfies*

$$\beta_{i_p}^p \pm \beta_{i_q}^q \notin R \text{ for } i_p \neq i_q \text{ and } 1 \leq p < q \leq 6.$$

Then all vectors in the subspace $\mathfrak{U}_{\beta_{i_1}^1} \oplus \mathfrak{U}_{\beta_{i_2}^2} \oplus \cdots \oplus \mathfrak{U}_{\beta_{i_6}^6}$ are structural equigeodesic vectors.

Proof. Let $X = \sum_{i=1}^6 X_{\mathfrak{m}_i} = X_{(1,0)} + X_{(0,1)} + X_{(1,1)} + X_{(2,1)} + X_{(3,1)} + X_{(3,2)}$, where

$$\begin{aligned} X_{(1,0)} &= \sum_{\alpha \in R^{\mathfrak{m}}(1,0)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\} = \sum_{\alpha \in R^{\mathfrak{m}}(1,0)} \mathfrak{U}_\alpha, & X_{(0,1)} &= \sum_{\alpha \in R^{\mathfrak{m}}(0,1)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\} = \sum_{\alpha \in R^{\mathfrak{m}}(0,1)} \mathfrak{U}_\alpha \\ X_{(1,1)} &= \sum_{\alpha \in R^{\mathfrak{m}}(1,1)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\} = \sum_{\alpha \in R^{\mathfrak{m}}(1,1)} \mathfrak{U}_\alpha, & X_{(2,1)} &= \sum_{\alpha \in R^{\mathfrak{m}}(2,1)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\} = \sum_{\alpha \in R^{\mathfrak{m}}(2,1)} \mathfrak{U}_\alpha \\ X_{(3,1)} &= \sum_{\alpha \in R^{\mathfrak{m}}(3,1)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\} = \sum_{\alpha \in R^{\mathfrak{m}}(3,1)} \mathfrak{U}_\alpha, & X_{(3,2)} &= \sum_{\alpha \in R^{\mathfrak{m}}(3,2)} \{\mathbb{R}A_\alpha + \mathbb{R}B_\alpha\} = \sum_{\alpha \in R^{\mathfrak{m}}(3,2)} \mathfrak{U}_\alpha. \end{aligned}$$

Since $\beta_{i_p}^p \pm \beta_{i_q}^q$ is not a root for $i_p \neq i_q$ and $1 \leq p < q \leq 6$, we have that $N_{\beta_{i_p}^p, \beta_{i_q}^q} = N_{-\beta_{i_p}^p, \beta_{i_q}^q} = N_{\beta_{i_p}^p, -\beta_{i_q}^q} = 0$. A direct computation using the relations of Lemma 2.2 shows that the system of equations (15) vanishes and the vector X is a structural equigeodesic vector. \square

Similarly, we can proof the following:

Theorem 3.6. *Let G/K be a generalized flag manifold with G_2 -type \mathfrak{t} -roots and $\Pi_K = \Pi \setminus \{\alpha_{i_0}, \alpha_{j_0}\}$ of Type II. Let the positive roots $R^{\mathfrak{n}}(1, 0) = \{\beta_1^1, \dots, \beta_{k_1}^1\}$, $R^{\mathfrak{n}}(0, 1) = \{\beta_1^2, \dots, \beta_{k_2}^2\}$, $R^{\mathfrak{n}}(1, 1) = \{\beta_1^3, \dots, \beta_{k_3}^3\}$, $R^{\mathfrak{n}}(1, 2) = \{\beta_1^4, \dots, \beta_{k_4}^4\}$, $R^{\mathfrak{n}}(1, 3) = \{\beta_1^5, \dots, \beta_{k_5}^5\}$, $R^{\mathfrak{n}}(2, 3) = \{\beta_1^6, \dots, \beta_{k_6}^6\}$. Suppose that the set $\{\beta_{i_1}^1, \beta_{i_2}^2, \dots, \beta_{i_6}^6 : 1 \leq i_1 \leq k_1, \dots, 1 \leq i_6 \leq k_6\}$ satisfies*

$$\beta_{i_p}^p \pm \beta_{i_q}^q \notin R \text{ for } i_p \neq i_q \text{ and } 1 \leq p < q \leq 6.$$

Then all vectors in the subspace $\mathfrak{U}_{\beta_{i_1}^1} \oplus \mathfrak{U}_{\beta_{i_2}^2} \oplus \dots \oplus \mathfrak{U}_{\beta_{i_6}^6}$ are structural equigeodesic vectors.

4. Structural Equigeodesic Vectors on Flag Manifolds with G_2 -type \mathfrak{t} -roots

In this section we give a family of structural equigeodesic vectors for generalized flag manifolds with G_2 -type \mathfrak{t} -roots, namely for $F_4/(U(3) \times U(1))$, $E_6/(U(3) \times U(3))$, $E_7/(U(6) \times U(1))$ and $E_8/(E_6 \times U(1) \times U(1))$. We classify the positive roots that satisfy the hypothesis of Theorems 3.5 and 3.6.

For the root system of exceptional Lie groups F_4, E_6, E_7 and E_8 we use the notation of [1], where all positive roots are given as linear combinations of the simple roots $\Pi = \{\alpha_1, \alpha_2, \dots, \alpha_\ell\}$ ($\ell = \text{rk } \mathfrak{g}^{\mathbb{C}}$).

4.1. Structural Equigeodesic vectors on the flag manifold $F_4/(U(3) \times U(1))$. Let $\Pi = \{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$ be a system of simple roots for F_4 with highest root $\tilde{\alpha} = 2\alpha_1 + 4\alpha_2 + 3\alpha_3 + 2\alpha_4$. The flag manifold $F_4/(U(3) \times U(1))$ is determined by $\Pi_K = \Pi \setminus \{\alpha_3, \alpha_4\}$. From Table 1 we have that the positive \mathfrak{t} -roots are given by $R_{\mathfrak{t}}^+ = \{\bar{\alpha}_3, \bar{\alpha}_4, \bar{\alpha}_3 + \bar{\alpha}_4, 2\bar{\alpha}_3 + \bar{\alpha}_4, 3\bar{\alpha}_3 + \bar{\alpha}_4, 3\bar{\alpha}_3 + 2\bar{\alpha}_4\}$. According to Proposition 2.8 (1), we obtain the decomposition (10) where the submodules \mathfrak{m}_i are defined by (8). The sets $R^{\mathfrak{m}}(j_1, j_2) = \{\sum_{i=1}^4 c_i \alpha_i \in R_M^+ : c_3 = j_1, c_4 = j_2\}$ are given explicitly as follows:

$$\begin{aligned} R^{\mathfrak{m}}(1, 0) &= \{e_3, e_1 - e_2, e_3 - e_4, e_3 + e_4, 1/2(e_1 - e_2 + e_3 + e_4), 1/2(e_1 - e_2 + e_3 - e_4)\} \\ &= \{\beta_1^1, \dots, \beta_6^1\} \\ R^{\mathfrak{m}}(0, 1) &= \{e_2 - e_3\} = \{\beta_1^2\} \\ R^{\mathfrak{m}}(1, 1) &= \{e_2, e_1 - e_3, e_2 - e_4, e_2 + e_4, 1/2(e_1 + e_2 - e_3 + e_4), 1/2(e_1 + e_2 - e_3 - e_4)\} \end{aligned}$$

$$\begin{aligned}
&= \{\beta_1^3, \dots, \beta_6^3\} \\
R^m(2, 1) &= \{e_1, e_1 - e_4, e_1 + e_4, e_2 + e_3, 1/2(e_1 + e_2 + e_3 + e_4), 1/2(e_1 + e_2 + e_3 - e_4)\} \\
&= \{\beta_1^4, \dots, \beta_6^4\} \\
R^m(3, 1) &= \{e_1 + e_3\} = \{\beta_1^5\} \\
R^m(3, 2) &= \{e_1 + e_2\} = \{\beta_1^6\}.
\end{aligned}$$

It is easy to see that the roots which satisfy the hypothesis of Theorem 3.5 are the following:

$$\beta_i^1 \pm \beta_j^3 \notin R \text{ for every } (i, j) \in \{(1, 3), (1, 4), (2, 5), (2, 6), (3, 1), (3, 6), (4, 1), (4, 5), (5, 2), (5, 4), (6, 2), (6, 3)\}$$

$$\beta_i^1 \pm \beta_j^4 \notin R \text{ for every } (i, j) \in \{(1, 2), (1, 3), (2, 5), (2, 6), (3, 1), (3, 5), (4, 1), (4, 6), (5, 2), (5, 4), (6, 3), (6, 4)\}$$

$$\beta_i^1 \pm \beta_1^6 \notin R \text{ for every } i = 1, 2, \dots, 6$$

$$\beta_1^2 \pm \beta_j^4 \notin R \text{ for every } j = 1, 2, \dots, 6$$

$$\beta_i^3 \pm \beta_j^4 \notin R \text{ for every } (i, j) \in \{(1, 2), (1, 3), (2, 5), (2, 6), (3, 1), (3, 5), (4, 1), (4, 6), (5, 2), (5, 4), (6, 3), (6, 4)\}$$

$$\beta_i^3 \pm \beta_1^5 \notin R \text{ for every } i = 1, 2, \dots, 6.$$

From the above roots we can find all the subspaces for which the vectors are structural equigeodesic vectors. In particular we have the following:

Proposition 4.1. *The root spaces for the generalized flag manifold $F_4 / (U(3) \times U(1))$ whose roots satisfy Theorem 3.5 are listed in Table 3. In particular, all vectors in these subspaces are structural equigeodesic vectors.*

Table 3. Structural equigeodesic vectors for $F_4 / (U(3) \times U(1))$

$\mathfrak{U}_{\beta_3^3} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_1^4} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_3^3} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_5^1}$	$\mathfrak{U}_{\beta_4^3} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_5^1}$
$\mathfrak{U}_{\beta_2^4} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_5^1}$	$\mathfrak{U}_{\beta_4^3} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_5^3} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_3^4} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_6^1}$
$\mathfrak{U}_{\beta_3^3} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_6^3} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_4^3} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_6^3} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_4^1}$
$\mathfrak{U}_{\beta_1^3} \oplus \mathfrak{U}_{\beta_4^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_5^3} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_1^4} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_2^3} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$
$\mathfrak{U}_{\beta_6^3} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_2^4} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_5^1}$	$\mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_3^1}$
$\mathfrak{U}_{\beta_3^4} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_4^4} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_6^1}$
$\mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_3^3} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_5^1}$	$\mathfrak{U}_{\beta_5^4} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_4^1} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_5^1}$
$\mathfrak{U}_{\beta_4^1} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_6^4} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_4^1}$
$\mathfrak{U}_{\beta_1^3} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_6^1} \oplus \mathfrak{U}_{\beta_2^1} \oplus \mathfrak{U}_{\beta_3^1}$	$\mathfrak{U}_{\beta_6^3} \oplus \mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_4^1}$	$\mathfrak{U}_{\beta_2^3} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$
$\mathfrak{U}_{\beta_6^3} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_2^1}$	$\mathfrak{U}_{\beta_1^2} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_2^1}$	$\mathfrak{U}_{\beta_1^5} \oplus \mathfrak{U}_{\beta_1^1} \oplus \mathfrak{U}_{\beta_2^1}$	$\mathfrak{U}_{\beta_3^1} \oplus \mathfrak{U}_{\beta_4^1} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$
$\mathfrak{U}_{\beta_3^4} \oplus \mathfrak{U}_{\beta_4^1} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$	$\mathfrak{U}_{\beta_3^3} \oplus \mathfrak{U}_{\beta_4^1} \oplus \mathfrak{U}_{\beta_5^1} \oplus \mathfrak{U}_{\beta_6^1}$		

4.2. Structural Equigeodesic vectors on the flag manifold $E_6 / (U(3) \times U(3))$. Let $\Pi = \{\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5, \alpha_6\}$ be a system of simple roots for E_6 with highest $\tilde{\alpha} = \alpha_1 + 2\alpha_2 + 3\alpha_3 +$

$2\alpha_4 + \alpha_5 + 2\alpha_6$. The flag manifold $E_6/(U(3) \times U(3))$ is determined by $\Pi_K = \Pi \setminus \{\alpha_3, \alpha_6\}$. From Table 1 we have that the the positive \mathfrak{t} -roots are given by $R_t^+ = \{\bar{\alpha}_3, \bar{\alpha}_6, \bar{\alpha}_3 + \bar{\alpha}_6, 2\bar{\alpha}_3 + \bar{\alpha}_6, 3\bar{\alpha}_3 + \bar{\alpha}_6, 3\bar{\alpha}_3 + 2\bar{\alpha}_6\}$. According to Proposition 2.8 (1), we obtain the decomposition (10) where the submodules \mathfrak{m}_i are defined by (8). The sets $R^{\mathfrak{m}}(j_1, j_2) = \{\sum_{i=1}^6 c_i \alpha_i \in R_M^+ : c_3 = j_1, c_6 = j_2\}$ are given explicitly as follows:

$$\begin{aligned} R^{\mathfrak{m}}(1, 0) &= \{e_3 - e_4, e_2 - e_4, e_3 - e_5, e_1 - e_4, e_1 - e_5, e_1 - e_6, e_2 - e_5, e_2 - e_6, e_3 - e_6\} \\ &= \{\beta_1^1, \dots, \beta_9^1\} \\ R^{\mathfrak{m}}(0, 1) &= \{e_4 + e_5 + e_6 + e\} = \{\beta_1^2\} \\ R^{\mathfrak{m}}(1, 1) &= \{e_1 + e_4 + e_6 + e, e_2 + e_4 + e_6 + e, e_3 + e_4 + e_5 + e, e_3 + e_5 + e_6 + e, \\ &\quad e_1 + e_4 + e_5 + e, e_1 + e_5 + e_6 + e, e_2 + e_4 + e_5 + e, e_2 + e_5 + e_6 + e, \\ &\quad e_3 + e_4 + e_6 + e\} = \{\beta_1^3, \dots, \beta_8^3\} \\ R^{\mathfrak{m}}(2, 1) &= \{e_1 + e_2 + e_5 + e, e_1 + e_3 + e_4 + e, e_1 + e_3 + e_6 + e, e_2 + e_3 + e_4 + e, \\ &\quad e_2 + e_3 + e_6 + e, e_1 + e_2 + e_4 + e, e_1 + e_2 + e_6 + e, e_1 + e_3 + e_5 + e, \\ &\quad e_2 + e_3 + e_5 + e\} = \{\beta_1^4, \dots, \beta_8^4\} \\ R^{\mathfrak{m}}(3, 1) &= \{e_1 + e_2 + e_3 + e\} = \{\beta_1^5\} \\ R^{\mathfrak{m}}(3, 2) &= \{e_1 + e_2 + e_3 + e_4 + e_5 + e_6 + 2e\} = \{\beta_1^6\}. \end{aligned}$$

It is easy to see that all roots which satisfy Theorem 3.5 are the following:

$$\beta_i^1 \pm \beta_j^3 \notin R \text{ for every } (i, j) \in \{(1, 3), (1, 6), (1, 8), (1, 9), (2, 2), (2, 4), (2, 6), (2, 7), (3, 1), (3, 2), (3, 3), (3, 4), (4, 1), (4, 4), (4, 5), (4, 8), (5, 2), (5, 5), (5, 6), (5, 9), (6, 1), (6, 3), (6, 6), (6, 7), (7, 1), (7, 7), (7, 8), (7, 9), (8, 2), (8, 3), (8, 5), (8, 8), (9, 4), (9, 5), (9, 7), (9, 9)\}$$

$$\beta_i^1 \pm \beta_j^4 \notin R \text{ for every } (i, j) \in \{(1, 1), (1, 2), (1, 4), (1, 7), (2, 3), (2, 4), (2, 6), (2, 8), (3, 6), (3, 7), (3, 8), (3, 9), (4, 2), (4, 5), (4, 6), (4, 9), (5, 1), (5, 4), (5, 5), (5, 8), (6, 3), (6, 4), (6, 7), (6, 9), (7, 1), (7, 2), (7, 3), (7, 9), (8, 2), (8, 5), (8, 7), (8, 8), (9, 1), (9, 3), (9, 5), (9, 6)\}$$

$$\beta_i^1 \pm \beta_1^6 \notin R \text{ for every } i = 1, 2, \dots, 9$$

$$\beta_1^2 \pm \beta_j^4 \notin R \text{ for every } j = 1, 2, \dots, 9$$

$$\beta_i^3 \pm \beta_j^4 \notin R \text{ for every } (i, j) \in \{(1, 1), (1, 4), (1, 5), (1, 8), (1, 9), (2, 1), (2, 2), (2, 3), (2, 8), (2, 9), (3, 1), (3, 3), (3, 5), (3, 6), (3, 7), (4, 1), (4, 2), (4, 4), (4, 6), (4, 7), (5, 3), (5, 4), (5, 5), (5, 7), (5, 9), (6, 2), (6, 4), (6, 5), (6, 6), (6, 9), (7, 2), (7, 3), (7, 5), (7, 7), (7, 8), (8, 2), (8, 3), (8, 4), (8, 6), (8, 8), (9, 1), (9, 6), (9, 7), (9, 8), (9, 9)\}$$

$$\beta_i^3 \pm \beta_1^5 \notin R \text{ for every } i = 1, 2, \dots, 9.$$

From the above roots we can find all the subspaces for which the vectors are structural equigeodesic vectors. More precisely, from the roots $\beta_i^1 \pm \beta_j^3 \notin R$, $\beta_i^1 \pm \beta_j^4 \notin R$, $\beta_i^1 \pm \beta_1^6 \notin R$, $\beta_1^2 \pm \beta_j^4 \notin R$ and $\beta_i^3 \pm \beta_1^5 \notin R$ we obtain the subspaces in the following tables:

Table 4. Structural equigeodesic vectors for $E_6/(U(3) \times U(3))$ [illegible]

Now from the roots $\beta_i^3 \pm \beta_i^4 \notin R$ we have the following subspaces:

Table 5. Structural equigeodesic vectors for $E_6 / (U(3) \times U(3))$ [illegible]

Hence we obtain the following:

Proposition 4.2. *The root spaces for the generalized flag manifold $E_6(\alpha_3, \alpha_6) = E_6 / (U(3) \times U(3))$, with all vectors are structural equigeodesic vectors are described in*

Tables 4 and 5.

4.3. Structural Equigeodesic vectors on the flag manifold $E_7/(U(6) \times U(1))$. Let $\Pi = \{\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5, \alpha_6, \alpha_7\}$ be a system of simple roots for E_7 with highest $\tilde{\alpha} = \alpha_1 + 2\alpha_2 + 3\alpha_3 + 4\alpha_4 + 3\alpha_5 + 2\alpha_6 + 2\alpha_7$. The flag manifold $E_7/(U(6) \times U(1))$ is determined by $\Pi_K = \Pi \setminus \{\alpha_5, \alpha_6\}$. From Table 1 we have that the positive \mathfrak{t} -roots are given by $R_t^+ = \{\bar{\alpha}_5, \bar{\alpha}_6, \bar{\alpha}_5 + \bar{\alpha}_6, 2\bar{\alpha}_5 + \bar{\alpha}_6, 3\bar{\alpha}_5 + \bar{\alpha}_6, 3\bar{\alpha}_5 + 2\bar{\alpha}_6\}$. According to Proposition 2.8 (1), we obtain the decomposition (10) where the submodules \mathfrak{m}_i are defined by (8). The sets $R^{\mathfrak{m}}(j_1, j_2) = \{\sum_{i=1}^7 c_i \alpha_i \in R_M^+ : c_5 = j_1, c_6 = j_2\}$ are given explicitly as follows:

$$\begin{aligned} R^{\mathfrak{m}}(1, 0) &= \{e_1 - e_6, e_2 - e_6, e_3 - e_6, e_4 - e_6, e_5 - e_6, e_4 + e_5 + e_7 + e_8, e_3 + e_5 + e_7 + e_8, \\ &\quad e_3 + e_4 + e_7 + e_8, e_2 + e_5 + e_7 + e_8, e_2 + e_2 + e_7 + e_8, e_2 + e_3 + e_7 + e_8, \\ &\quad e_1 + e_5 + e_7 + e_8, e_1 + e_4 + e_7 + e_8, e_1 + e_3 + e_7 + e_8, e_1 + e_2 + e_7 + e_8\} \\ &= \{\beta_1^1, \dots, \beta_{15}^1\} \\ R^{\mathfrak{m}}(0, 1) &= \{e_6 - e_7\} = \{\beta_1^2\} \\ R^{\mathfrak{m}}(1, 1) &= \{e_1 - e_7, e_2 - e_7, e_3 - e_7, e_4 - e_7, e_5 - e_7, e_4 + e_5 + e_6 + e_8, e_3 + e_5 + e_6 + e_8, \\ &\quad e_3 + e_4 + e_6 + e_8, e_2 + e_5 + e_6 + e_8, e_2 + e_4 + e_6 + e_8, e_2 + e_3 + e_6 + e_8, \\ &\quad e_1 + e_5 + e_6 + e_8, e_1 + e_4 + e_6 + e_8, e_1 + e_3 + e_6 + e_8, e_1 + e_2 + e_6 + e_8\} \\ &= \{\beta_1^3, \dots, \beta_{15}^3\} \\ R^{\mathfrak{m}}(2, 1) &= \{e_3 + e_4 + e_5 + e_8, e_2 + e_4 + e_5 + e_8, e_2 + e_3 + e_5 + e_8, e_2 + e_3 + e_4 + e_8, \\ &\quad e_1 + e_4 + e_5 + e_8, e_1 + e_3 + e_5 + e_8, e_1 + e_3 + e_4 + e_8, e_1 + e_2 + e_5 + e_8, \\ &\quad e_1 + e_2 + e_4 + e_8, e_1 + e_2 + e_3 + e_8, -(e_1 - e_8), -(e_2 - e_8), -(e_3 - e_8), \\ &\quad -(e_4 - e_8), -(e_5 - e_8)\} = \{\beta_1^4, \dots, \beta_{15}^4\} \\ R^{\mathfrak{m}}(3, 1) &= \{-(e_6 - e_8)\} = \{\beta_1^5\} \\ R^{\mathfrak{m}}(3, 2) &= \{-(e_7 - e_8)\} = \{\beta_1^6\}. \end{aligned}$$

The roots which satisfy Theorem 3.5 are the following:

$$\begin{aligned} &\beta_1^1 \pm \beta_j^3, j = 2, 3, 4, 5, 12, 13, 14, 15; \beta_2^1 \pm \beta_j^3, j = 1, 3, 4, 5, 9, 10, 11, 15; \beta_3^1 \pm \beta_j^3, j = 1, 2, 4, 5, 7, 8, 11, 14; \\ &\beta_3^1 \pm \beta_j^3, j = 1, 2, 4, 5, 7, 8, 11, 14; \beta_4^1 \pm \beta_j^3, j = 1, 2, 3, 5, 6, 8, 10, 13; \beta_5^1 \pm \beta_j^3, j = 1, 2, 3, 4, 6, 7, 9, 12; \beta_6^1 \pm \\ &\beta_j^3, j = 4, 5, 7, 8, 9, 10, 12, 13; \beta_7^1 \pm \beta_j^3, j = 3, 5, 6, 8, 9, 11, 12, 14; \beta_8^1 \pm \beta_j^3, j = 3, 4, 6, 7, 10, 11, 13, 14; \beta_9^1 \pm \\ &\beta_j^3, j = 2, 5, 6, 7, 10, 11, 12, 15; \beta_{10}^1 \pm \beta_j^3, j = 2, 4, 6, 8, 9, 11, 13, 15; \beta_{11}^1 \pm \beta_j^3, j = 2, 3, 7, 8, 9, 10, 14, 15; \beta_{12}^1 \pm \\ &\beta_j^3, j = 1, 5, 6, 7, 9, 13, 14, 15; \beta_{13}^1 \pm \beta_j^3, j = 1, 4, 5, 6, 8, 10, 12, 14, 15; \beta_{14}^1 \pm \beta_j^3, j = 1, 3, 7, 8, 11, 12, 13, 15; \\ &\beta_{15}^1 \pm \beta_j^3, j = 1, 2, 9, 10, 11, 12, 13, 14; \beta_1^1 \pm \beta_j^4, j = 1, 2, 3, 4, 12, 13, 14, 15; \beta_2^1 \pm \beta_j^4, j = 1, 5, 6, 7, 11, 13, 14, 15; \\ &\beta_3^1 \pm \beta_j^4, j = 2, 5, 8, 9, 11, 12, 14, 15; \beta_4^1 \pm \beta_j^4, j = 3, 6, 8, 10, 11, 12, 13, 15; \beta_5^1 \pm \beta_j^4, j = 4, 7, 9, 10, 11, 12, 13, 14; \\ &\beta_6^1 \pm \beta_j^4, j = 3, 4, 6, 7, 8, 9, 14, 15; \beta_7^1 \pm \beta_j^4, j = 2, 4, 5, 7, 8, 10, 13, 15; \beta_8^1 \pm \beta_j^4, j = 2, 3, 5, 6, 9, 10, 13, 14; \\ &\beta_9^1 \pm \beta_j^4, j = 1, 4, 5, 6, 9, 10, 12, 15; \beta_{10}^1 \pm \beta_j^4, j = 1, 3, 5, 7, 8, 10, 12, 4; \beta_{11}^1 \pm \beta_j^4, j = 1, 2, 6, 7, 8, 9, 12, 13; \\ &\beta_{12}^1 \pm \beta_j^4, j = 1, 2, 3, 7, 9, 10, 11, 15; \beta_{13}^1 \pm \beta_j^4, j = 1, 2, 4, 6, 8, 10, 11, 14; \beta_{14}^1 \pm \beta_j^4, j = 1, 3, 4, 5, 8, 9, 11, 13; \\ &\beta_{15}^1 \pm \beta_j^4, j = 2, 3, 4, 5, 6, 7, 11, 12; \beta_1^3 \pm \beta_j^4, j = 1, 2, 3, 4, 12, 13, 14, 15; \beta_2^3 \pm \beta_j^4, j = 1, 5, 6, 7, 11, 13, 14, 15; \\ &\beta_3^3 \pm \beta_j^4, j = 2, 5, 8, 9, 11, 12, 14, 15; \beta_4^3 \pm \beta_j^4, j = 3, 6, 8, 10, 11, 12, 13, 15; \beta_5^3 \pm \beta_j^4, j = 4, 7, 9, 10, 11, 12, 13, 14; \\ &\beta_6^3 \pm \beta_j^4, j = 3, 4, 6, 7, 8, 9, 14, 15; \beta_7^3 \pm \beta_j^4, j = 2, 4, 5, 7, 8, 10, 13, 15; \beta_8^3 \pm \beta_j^4, j = 2, 3, 5, 6, 9, 10, 13, 14; \\ &\beta_9^3 \pm \beta_j^4, j = 1, 4, 5, 6, 9, 10, 12, 15; \beta_{10}^3 \pm \beta_j^4, j = 1, 3, 5, 7, 8, 10, 12, 14; \beta_{11}^3 \pm \beta_j^4, j = 1, 2, 6, 7, 8, 9, 12, 13; \\ &\beta_{12}^3 \pm \beta_j^4, j = 1, 2, 3, 7, 9, 10, 11, 15; \beta_{13}^3 \pm \beta_j^4, j = 1, 2, 4, 6, 8, 10, 11, 14; \beta_{14}^3 \pm \beta_j^4, j = 1, 3, 4, 5, 8, 9, 11, 13; \\ &\beta_{15}^3 \pm \beta_j^4, j = 2, 3, 4, 5, 6, 7, 11, 12; \beta_i^2 \pm \beta_j^4, j = 1, 2, \dots, 15; \beta_1^2 \pm \beta_j^4, j = 1, 2, \dots, 15; \beta_i^3 \pm \beta_j^5, j = 1, 2, \dots, 15. \end{aligned}$$

By applying the conclusion of Theorem 3.5 we can find all subspaces on which the vectors are structural equigeodesics. Some of them are the following:

$$\left\{ \begin{array}{l} \mathbb{U}_{\beta_1^1} \oplus_{j=2}^5 \mathbb{U}_{\beta_j^3} \oplus_{k=12}^{15} \mathbb{U}_{\beta_k^3} \quad \mathbb{U}_{\beta_1^1} \oplus_{j=1}^4 \mathbb{U}_{\beta_j^4} \oplus_{k=12}^{15} \mathbb{U}_{\beta_k^4} \quad \mathbb{U}_{\beta_1^6} \oplus_{i=1}^{15} \mathbb{U}_{\beta_i^1} \\ \mathbb{U}_{\beta_1^5} \oplus_{i=1}^{15} \mathbb{U}_{\beta_i^3} \quad \mathbb{U}_{\beta_1^3} \oplus_{i=1}^4 \mathbb{U}_{\beta_i^4} \oplus_{k=12}^{15} \mathbb{U}_{\beta_k^4} \quad \mathbb{U}_{\beta_5^3} \oplus \mathbb{U}_{\beta_4^4} \oplus \mathbb{U}_{\beta_7^4} \oplus_{i=9}^{14} \mathbb{U}_{\beta_i^4} \\ \mathbb{U}_{\beta_1^2} \oplus_{i=1}^{15} \mathbb{U}_{\beta_i^4} \quad \mathbb{U}_{\beta_5^1} \oplus \mathbb{U}_{\beta_{12}^3} \oplus \mathbb{U}_{\beta_{12}^4} \quad \mathbb{U}_{\beta_1^9} \oplus \mathbb{U}_{\beta_5^3} \oplus \mathbb{U}_{\beta_{10}^3} \oplus \mathbb{U}_{\beta_{15}^3} \oplus \mathbb{U}_{\beta_5^4} \oplus \mathbb{U}_{\beta_{10}^4} \oplus \mathbb{U}_{\beta_{15}^4} \end{array} \right\}$$

$$\dots\dots\dots \left\{ \begin{array}{l} \mathbb{U}_{\beta_{11}^1} \oplus \mathbb{U}_{\beta_{14}^3} \oplus \mathbb{U}_{\beta_3^4} \oplus \mathbb{U}_{\beta_8^4} \oplus \mathbb{U}_{\beta_9^4} \quad \mathbb{U}_{\beta_{14}^3} \oplus_{i=3}^7 \mathbb{U}_{\beta_i^4} \oplus \mathbb{U}_{\beta_1^4} \oplus \mathbb{U}_{\beta_{11}^4} \oplus \mathbb{U}_{\beta_{13}^4} \\ \mathbb{U}_{\beta_3^1} \oplus \mathbb{U}_{\beta_4^3} \oplus \mathbb{U}_{\beta_8^4} \oplus \mathbb{U}_{\beta_{11}^4} \oplus \mathbb{U}_{\beta_{12}^4} \oplus \mathbb{U}_{\beta_{15}^4} \quad \mathbb{U}_{\beta_{14}^1} \oplus_{i=3}^5 \mathbb{U}_{\beta_i^4} \oplus \mathbb{U}_{\beta_1^4} \oplus \mathbb{U}_{\beta_{11}^4} \oplus \mathbb{U}_{\beta_8^4} \oplus \mathbb{U}_{\beta_9^4} \oplus \mathbb{U}_{\beta_{13}^4} \\ \mathbb{U}_{\beta_7^1} \oplus \mathbb{U}_{\beta_8^3} \oplus \mathbb{U}_{\beta_2^4} \oplus \mathbb{U}_{\beta_5^4} \oplus \mathbb{U}_{\beta_{10}^4} \oplus \mathbb{U}_{\beta_{11}^4} \quad \mathbb{U}_{\beta_{15}^1} \oplus \mathbb{U}_{\beta_{14}^3} \oplus \mathbb{U}_{\beta_3^4} \oplus \mathbb{U}_{\beta_4^4} \oplus \mathbb{U}_{\beta_5^4} \oplus \mathbb{U}_{\beta_{11}^4} \\ \mathbb{U}_{\beta_3^1} \oplus \mathbb{U}_{\beta_3^3} \oplus \mathbb{U}_{\beta_2^4} \oplus \mathbb{U}_{\beta_5^4} \oplus \mathbb{U}_{\beta_8^4} \oplus \mathbb{U}_{\beta_{11}^4} \oplus \mathbb{U}_{\beta_{14}^4} \quad \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_3^1} \oplus \mathbb{U}_{\beta_{11}^1} \oplus \mathbb{U}_{\beta_{12}^1} \oplus \mathbb{U}_{\beta_2^4} \\ \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_5^3} \oplus \mathbb{U}_{\beta_6^1} \oplus \mathbb{U}_{\beta_4^4} \oplus \mathbb{U}_{\beta_7^4} \quad \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_3^1} \oplus \mathbb{U}_{\beta_8^1} \oplus \mathbb{U}_{\beta_{14}^1} \oplus \mathbb{U}_{\beta_5^4} \\ \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_3^1} \oplus \mathbb{U}_{\beta_6^1} \oplus \mathbb{U}_{\beta_8^4} \oplus \mathbb{U}_{\beta_{15}^4} \quad \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_8^1} \oplus \mathbb{U}_{\beta_{12}^1} \oplus \mathbb{U}_{\beta_{10}^4} \oplus \mathbb{U}_{\beta_{15}^4} \\ \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_6^1} \oplus \mathbb{U}_{\beta_{11}^1} \oplus \mathbb{U}_{\beta_7^4} \oplus \mathbb{U}_{\beta_8^4} \quad \mathbb{U}_{\beta_7^3} \oplus \mathbb{U}_{\beta_{11}^1} \oplus \mathbb{U}_{\beta_{12}^1} \oplus \mathbb{U}_{\beta_{14}^1} \oplus \mathbb{U}_{\beta_4^4} \oplus \mathbb{U}_{\beta_8^4} \oplus \mathbb{U}_{\beta_8^4} \\ \mathbb{U}_{\beta_1^1} \oplus \mathbb{U}_{\beta_3^3} \oplus \mathbb{U}_{\beta_4^4} \oplus_{i=12}^{15} \mathbb{U}_{\beta_i^3} \oplus \mathbb{U}_{\beta_2^4} \oplus \mathbb{U}_{\beta_3^4} \oplus_{i=12}^{15} \mathbb{U}_{\beta_i^4} \quad \mathbb{U}_{\beta_{12}^1} \oplus \mathbb{U}_{\beta_1^3} \oplus \mathbb{U}_{\beta_9^3} \oplus \mathbb{U}_{\beta_{15}^3} \oplus \mathbb{U}_{\beta_1^4} \oplus \mathbb{U}_{\beta_9^4} \oplus \mathbb{U}_{\beta_{15}^4} \\ \dots \quad \dots \end{array} \right\}$$

4.4. Structural Equigeodesic vectors on the flag manifold $E_8/(E_6 \times U(1) \times U(1))$. Let $\Pi = \{\alpha_1, \alpha_2, \alpha_3, \alpha_4, \alpha_5, \alpha_6, \alpha_7, \alpha_8\}$ be a system of simple roots for E_8 with highest $\tilde{\alpha} = 2\alpha_1 + 3\alpha_2 + 4\alpha_3 + 5\alpha_4 + 6\alpha_5 + 4\alpha_6 + 2\alpha_7 + 3\alpha_8$. The flag manifold $E_8/(E_6 \times U(1) \times U(1))$ is determined by $\Pi_K = \Pi \setminus \{\alpha_1, \alpha_2\}$. From Table 1 we have that the positive t-roots are given by $R_t^+ = \{\bar{\alpha}_1, \bar{\alpha}_1, \bar{\alpha}_1 + \bar{\alpha}_2, \bar{\alpha}_1 + 2\bar{\alpha}_2, \bar{\alpha}_1 + 3\bar{\alpha}_2, 2\bar{\alpha}_1 + 3\bar{\alpha}_2\}$. According to Proposition 2.8 (1), we obtain the decomposition (10) where the submodules m_i are defined by (8). The sets $R^n(j_1, j_2) = \{\sum_{i=1}^8 c_i \alpha_i \in R_M^+ : c_1 = j_1, c_2 = j_2\}$ are given explicitly as follows:

$$\begin{aligned} R^n(1, 0) &= \{e_1 - e - 2\} = \{\beta_1^1\} \\ R^n(0, 1) &= \{e_2 - e_i, i = 3, 4, 5, 6, 7, 8, e_2 + e_3 + e_i, i = 4, 5, 6, 7, 8, e_2 + e_4 + e_i, \\ &\quad i = 5, 6, 7, 8, e_2 + e_5 + e_i, i = 6, 7, 8, e_2 + e_6 + e_i, i = 7, 8, e_2 + e_7 + e_8, \\ &\quad -(e_1 + e_i + e_9), i = 3, 4, 5, 6, 7, 8\} = \{\beta_1^2, \dots, \beta_{27}^2\} \\ R^n(1, 1) &= \{e_1 - e_i, i = 3, 4, 5, 6, 7, 8, e_1 + e_3 + e_i, i = 4, 5, 6, 7, 8, e_1 + e_4 + e_i, \\ &\quad i = 5, 6, 7, 8, e_1 + e_5 + e_i, i = 6, 7, 8, e_1 + e_6 + e_i, i = 7, 8, e_1 + e_7 + e_8, \\ &\quad -(e_2 + e_i + e_9), i = 3, 4, 5, 6, 7, 8\} = \{\beta_1^3, \dots, \beta_{27}^3\} \\ R^n(1, 2) &= \{e_i - e_9, e_1 + e_2 + e_i, i = 3, 4, 5, 6, 7, 8, -(e_3 + e_i + e_9), i = 4, 5, 6, 7, 8, \\ &\quad -(e_4 + e_i + e_9), i = 5, 6, 7, 8, -(e_5 + e_i + e_9), i = 6, 7, 8, -(e_6 + e_i + e_9), \\ &\quad i = 7, 8, -(e_7 + e_8 + e_9)\} = \{\beta_1^4, \dots, \beta_{27}^4\} \\ R^n(1, 3) &= \{e_2 - e_9\} = \{\beta_1^5\} \\ R^n(2, 3) &= \{e_1 - e_9\} = \{\beta_1^6\} \end{aligned}$$

Below we list some roots which satisfy Theorem 3.6:

$\beta_1^1 \pm \beta_j^4, \beta_1^6 \pm \beta_j^2, \beta_1^5 \pm \beta_j^3, j = 1, 2, \dots, 27; \beta_1^2 \pm \beta_j^3, j = 2, 3, 4, 5, 6, 12, \dots, 22; \beta_2^2 \pm \beta_j^3, j = 1, 3, 4, 5, 6, 8, 9, 10, 11, 16, 17, 18, 19, 20, 21, 23; \beta_3^2 \pm \beta_j^3, j = 1, 2, 4, 5, \dots, 11, 13, 14, 15, 19, 20, 21, 24; \beta_4^2 \pm \beta_j^3, j = 1, 2, 3, 5, 6, 7, 8, 10, 11, 12, 14, 15, 17, 18, 21, 25; \beta_5^2 \pm \beta_j^3, j = 1, \dots, 9, 11, 12, 13, 15, 16, 18, 20, 26; \beta_6^2 \pm \beta_j^3, j = 1, 2, 3, 4, 5, 7, 8, 9, 10, 12, 13, 14, 16, 17, 19, 27; \beta_7^2 \pm \beta_j^3, j = 3, 4, 5, 6, 8, 9, 10, 11, 12, 13, 14, 15, 22, \dots, 27, \dots$

$\beta_1^2 \pm \beta_j^4, j = 2, 3, 4, 5, 6, 7, 18, \dots, 27; \beta_2^2 \pm \beta_j^4, j = 1, 3, 4, 5, 6, 8, 14, 15, 16, 17, 22, \dots, 27; \beta_3^2 \pm \beta_j^4, j = 1, 2, 4, 5, 6, 13, \dots, 17, 19, 20, 21, 25, 26, 27; \beta_4^2 \pm \beta_j^4, j = 1, 2, 3, 5, 6, 10, 13, 14, 16, 17, 18, 20, 21, 23, 24, 27; \beta_5^2 \pm$

$\beta_j^4, j = 1, 2, 3, 4, 6, 11, 13, 14, 15, 17, 18, 19, 21, 22, 24, 26; \beta_6^2 \pm \beta_j^4, j = 1, 2, 3, 4, 5, 12, 13, 14, 15, 16, 18, 18, 20, 22, 23, 25; \beta_7^2 \pm \beta_j^4, j = 3, 4, 5, 6, 9, 11, 12, \dots, 18, \dots$

$\beta_1^3 \pm \beta_j^4, j = 2, 3, 4, 5, 6, 7, 18, 19, 20, \dots, 27; \beta_2^3 \pm \beta_j^4, j = 1, 3, 4, 5, 6, 8, 14, 15, 16, 17, 22, \dots, 27; \beta_3^3 \pm \beta_j^4, j = 1, 2, 4, 5, 6, 9, 13, 15, 16, 17, 19, 20, 21, 25, 26, 27; \beta_4^3 \pm \beta_j^4, j = 1, 2, 3, 5, 6, 10, 13, 14, 16, 17, 18, 20, 21, 23, 24, 27; \beta_5^3 \pm \beta_j^4, j = 1, 2, 3, 4, 6, 11, 13, 14, 15, 17, 18, 19, 21, 22, 24, 27; \beta_6^3 \pm \beta_j^4, j = 1, 2, 3, 4, 5, 13, 14, 15, 16, 18, 19, 20, 22, 23, 25, 27; \beta_7^3 \pm \beta_j^4, j = 3, 4, 5, 6, 9, 10, 11, 12, 14, \dots, 21, \dots$

From these roots we can find some subspaces for which the vectors are structural equigeodesics. In particular we have:

$$\left\{ \begin{array}{ll} \mathfrak{U}_{\beta_1^1 \oplus \beta_{i=1}^{27}} \mathfrak{U}_{\beta_j^4}, \mathfrak{U}_{\beta_1^6 \oplus \beta_{i=1}^{27}} \mathfrak{U}_{\beta_j^2} & \mathfrak{U}_{\beta_1^5 \oplus \beta_{i=1}^{27}} \mathfrak{U}_{\beta_j^3} \\ \mathfrak{U}_{\beta_1^1 \oplus \beta_{i=3}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=22}^{27}} \mathfrak{U}_{\beta_j^4} & \mathfrak{U}_{\beta_2^2 \oplus \beta_{i=3}^6} \mathfrak{U}_{\beta_j^1 \oplus \beta_{j=22}^{27}} \mathfrak{U}_{\beta_j^4} \\ \mathfrak{U}_{\beta_2^2 \oplus \beta_{i=4}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=15}^{17}} \mathfrak{U}_{\beta_j^4 \oplus \beta_{k=25}^{27}} \mathfrak{U}_{\beta_k^4} & \mathfrak{U}_{\beta_6^2 \oplus \beta_{i=3}^5} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=14}^{16}} \mathfrak{U}_{\beta_j^4 \oplus \beta_{k=18}^{20}} \mathfrak{U}_{\beta_k^4} \\ \mathfrak{U}_{\beta_7^2 \oplus \beta_{i=3}^5} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=13}^{16}} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=18}^{27}} & \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=2}^6} \mathfrak{U}_{\beta_j^3 \oplus \beta_{j=12}^{22}} \mathfrak{U}_{\beta_j^3} \\ \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=3}^6} \mathfrak{U}_{\beta_j^3 \oplus \beta_{j=16}^{21}} \mathfrak{U}_{\beta_j^3} & \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=2}^6} \mathfrak{U}_{\beta_j^3 \oplus \beta_{j=19}^{21}} \mathfrak{U}_{\beta_j^3} \\ \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=2}^7} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=18}^{27}} \mathfrak{U}_{\beta_j^4} & \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=3}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=22}^{27}} \mathfrak{U}_{\beta_j^4} \\ \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=4}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=25}^{27}} \mathfrak{U}_{\beta_j^4} & \mathfrak{U}_{\beta_1^3 \oplus \beta_{i=2}^7} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=18}^{27}} \mathfrak{U}_{\beta_j^4} \\ \mathfrak{U}_{\beta_1^3 \oplus \beta_{i=3}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=22}^{27}} \mathfrak{U}_{\beta_j^4} & \mathfrak{U}_{\beta_1^3 \oplus \beta_{i=4}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=25}^{27}} \mathfrak{U}_{\beta_j^4} \\ \mathfrak{U}_{\beta_1^2 \oplus \beta_{i=5}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=23}^{24}} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=27}^{27}} & \mathfrak{U}_{\beta_1^3 \oplus \beta_{i=4}^6} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=25}^{27}} \mathfrak{U}_{\beta_j^4} \\ \mathfrak{U}_{\beta_3^2 \oplus \beta_{i=1}^2} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=13}^{14}} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=6}^{24}} \mathfrak{U}_{\beta_{j=17}^{24}} \mathfrak{U}_{\beta_{j=21}^{24}} & \mathfrak{U}_{\beta_4^3 \oplus \beta_{i=1}^3} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=13}^{14}} \mathfrak{U}_{\beta_j^4 \oplus \beta_{j=18}^{24}} \\ \dots & \dots \end{array} \right\}$$

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